

**Neighborhood**  
 PCA1, PCA2, PCA3  
 SPHER  
 LINEA  
 PLANA  
 DIP  
 DIPDIR  
 ROUGH  
 NBPTS  
 CURV  
 ZRANGE  
 ZMAX, ZMIN  
 ANISO  
 FOM

**FEAT**

**Point**  
 INT            NIR  
 X,Y, Z        NORMDIP  
 NBRET        NORMDIPDIR  
 RETNB        M3C2  
 ECHORAT     PCV  
 R, G, B       SF

**Context**  
 DZ  
 DH

**kNN**    \_    **SC0**    \_    **LBL**    \_    **Class**

DZ5\_SC0\_CTX\_1

\_    **SCx**    \_    **LBL**    \_    **Class**

DZ\_SCx\_CTX\_5

\_    **SC4.2**    \_    **LBL**    \_    **Class**

DZ\_SC5.5\_CTX\_2

ROUGH\_SC10.0\_PC1\_PC2\_MINUS  
 ROUGH\_SC10.0\_PC1  
 ROUGH\_SC10.0\_PC2

**SCx**    \_    **LBL1**

**SC4.2**    \_    **LBL1**

**SC0**    \_    **LBL1**

**SCx**    \_    **STAT**    \_    **LBL1**

**SC4.2**    \_    **STAT**    \_    **LBL1**

MEAN  
 MODE  
 MEDIAN  
 STD  
 RANGE  
 SKEW

INT\_SC0\_PC1\_PC2\_DIVIDE  
 Z\_SCx\_MEAN\_PC1\_PC2\_MINUS

**Optional**

_	<b>LBL2</b>	_	<b>MATH</b>
			PLUS MINUS MULTIPLY DIVIDE

**Dual cloud predictors**

- LBL, LBL1 & LBL2 are cloud labels
- kNN (k Nearest Neighbors) shall be an integer
- Class shall be an integer
- 4.2 is a float !
- If FEAT is SF, it shall be followed by an index as in SF42